

R-2000iB™ Series

Basic Description

The R-2000iB-series is FANUC Robotics' latest-generation, six-axis, heavy payload, high-performance family of industrial robots. The R-2000iB provides higher rates through industry-leading performance, reliability and maintainability, and is supported by our extensive service and parts network.

R-2000iB Series, the Solution for:

- Automotive spot welding and general assembly
- General industrial applications
- Material handling
- Part transfer
- Material removal
- Drilling
- Machine loading

Benefits

- One arm and wrist assemblies minimize interference with system peripherals and allow operation in confined spaces.
- Large allowable wrist moments and inertias meet a variety of heavy handling challenges.
- Many process attachment points make integration easier.
- Non-rotating forearm simplifies hose and cable dress-out to prolong service life.
- Proven, reliable FANUC servo drives provide highest uptime and productivity.
- Longer maintenance intervals equate to lower operating costs.
- Fewer mechanical components reduce drive time, increase mean time between failure (MTBF) and minimize spare part requirements.
- High-performance motion yields fast cycle times and high throughput.
- Wrist design and base mounting are identical to the R-2000iA, allowing for seamless customer compatibility.
- R-2000iB can reach all areas of R-2000iA work envelope for easy replacement.

Note: iPPAC™ and FoundryPPAC™ are registered trademarks of FANUC LTD.



Features

Mechanical

- Large work envelope with ability to reach overhead and behind.
- 6 axes of motion.
- Slim-profile design.
- PM reducers on all axes.
- Lack of counterweight increases available workspace.
- Process attachment cables routed through the arm.
- Piv-motors at wrist.
- Standard J1 adjustable hand stop.
- IP67 rated wrist/seam.

Control

- 30% average faster TTP and PAMP™ execution speed over previous generation.
- Up to 24 axes on main servo card plus 10 axes on mini-slot card for 40 axes maximum.
- Quick change amplifier <5 minutes.
- Fast load time <30 seconds.
- True Ethernet ports standard.
- USB interface on panel and PC/MCA slot internal.
- Easy connections to a variety of I/O, including a number of distributed I/O networks.
- iPanel™, a color, internet-ready touch pendant for even easier programming and system set-up interface design.
- Built-in support for machine vision applications for error proofing and robot guidance, without the need for a PC.

Options

- Process specific software packages for various applications.
- Web-based software tools for remote connectivity, diagnostics and production monitoring.
- FANUC's iMotion™ (Integrated Robot Vision) system delivers high performance 2-D and 3-D machine vision capabilities with FANUC reliability. Additional option for Error Proofing can provide integrated vision based capabilities to check for product compliance before product is packaged or further operations are performed.
- Foundry PPO™ protection package and two-part epoxy paint for foundry and harsh environments.
- Standard baseplate for quick robot installation.
- Auxiliary axes packages for integration of peripheral servo-controlled devices and robot track units.
- Adjustable hand stops for J1, J2 and J3.
- Various robot connection cable lengths for flexible customer placement and optional track rated cables.
- Pendant with touch screen for custom HMI applications.
- Monochrome touch pendant.
- Integrated spot welding utilities.
- Electrically insulated receptacle.

FANUC
Robotics

Fanuc User Manual Robot

Jessica J Manson



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Advances in Italian Mechanism Science Giuseppe Quaglia, Giovanni Boschetti, Giuseppe Carbone, 2024-08-01 This book presents the proceedings of the 5th International Conference of IFToMM ITALY IFIT held in Turin Italy on September 11-13 2024 It includes peer reviewed papers on the latest advances in mechanism and machine science discussing topics such as biomechanical engineering computational kinematics the history of mechanism and machine science gearing and transmissions multi body dynamics robotics and mechatronics the dynamics of machinery tribology vibrations rotor dynamics and vehicle dynamics A valuable up to date resource it offers an essential overview of the subject for scientists and practitioners alike and inspires further investigations and research *Robotic Welding, Intelligence and Automation*

Tzyh-Jong Tarn, Shan-Ben Chen, Xiao-Qi Chen, 2015-07-15 The primary aim of this volume is to provide researchers and engineers from both academic and industry with up to date coverage of new results in the field of robotic welding intelligent systems and automation The book is mainly based on papers selected from the 2014 International Conference on Robotic Welding Intelligence and Automation RWIA 2014 held Oct 25-27 2014 at Shanghai China The articles show that the intelligentized welding manufacturing IWM is becoming an inevitable trend with the intelligentized robotic welding as the key technology The volume is divided into four logical parts Intelligent Techniques for Robotic Welding Sensing of Arc Welding Processing Modeling and Intelligent Control of Welding Processing as well as Intelligent Control and its Applications in Engineering **Advances in Mechanism Design IV** Jaroslav Beran, Martin Bílek, Miroslav Václavík, Petr Žabka, 2024-08-30 This book presents the latest research advances relating to machines and mechanisms Featuring papers from the XIV International Conference on the Theory of Machines and Mechanisms TMM held in Liberec Czech Republic on September 3-5 2024 it includes a selection of the most important new results and developments The book is divided into five parts representing a well balanced overview and spanning the general theory of machines and mechanisms through analysis and synthesis of planar and spatial mechanisms linkages and cams robots and manipulators dynamics of machines and mechanisms rotor dynamics computational mechanics vibration and noise in machines optimization of mechanisms and machines mechanisms of textile machines mechatronics and control and monitoring systems of machines This conference is traditionally held every four years under the auspices of the international organisation IFToMM and the Czech Society for Mechanics *Vehicle and Automotive Engineering 4* Károly Jármai, Ákos Cservedák, 2022-09-09 This book presents the selected proceedings of the third fourth Vehicle and Automotive Engineering conference reflecting the outcomes of theoretical and practical studies and outlining future development trends in a broad field of automotive research The conference's main themes included design manufacturing economic and educational topics **Intelligent Control, Robotics, and Industrial Automation** Sanjay Sharma, Bidyadhar Subudhi, Umesh Kumar Sahu, 2023-11-17 This volume comprises peer reviewed proceedings of the International Conference on Robotics Control Automation and Artificial

Intelligence RCAA 2022 It aims to provide a broad spectrum picture of the state of art research and development in the areas of intelligent control the Internet of Things machine vision cybersecurity robotics circuits and sensors among others This volume will provide a valuable resource for those in academia and industry **CAD/CAM, Robotics, and Factories of the Future** Raj Gill, Chanan S. Syan, 1996 Advances in Mechanism Design III Jaroslav Beran, Martin Bílek, Miroslav Václavík, Petr Žabka, 2021-08-03 This book presents the latest research advances relating to machines and mechanisms Featuring papers from the XIII International Conference on the Theory of Machines and Mechanisms TMM 2020 held in Liberec Czech Republic on September 7-9 2021 it includes a selection of the most important new results and developments The book is divided into five parts representing a well balanced overview and spanning the general theory of machines and mechanisms through analysis and synthesis of planar and spatial mechanisms linkages and cams robots and manipulators dynamics of machines and mechanisms rotor dynamics computational mechanics vibration and noise in machines optimization of mechanisms and machines mechanisms of textile machines mechatronics and control and monitoring systems of machines This conference is traditionally held every four years under the auspices of the international organisation IFToMM and the Czech Society for Mechanics **Mobile Robots II** William J. Wolfe, Wendell H. Chun, 1988 **Theory and Design of CNC Systems** Suk-Hwan Suh, Seong Kyoong Kang, Dae-Hyuk Chung, Ian Stroud, 2008-08-22 Computer Numerical Control CNC controllers are high value added products counting for over 30% of the price of machine tools The development of CNC technology depends on the integration of technologies from many different industries and requires strategic long term support Theory and Design of CNC Systems covers the elements of control the design of control systems and modern open architecture control systems Topics covered include Numerical Control Kernel NCK design of CNC Programmable Logic Control PLC and the Man Machine Interface MMI as well as the major modules for the development of conversational programming methods The concepts and primary elements of STEP NC are also introduced A collaboration of several authors with considerable experience in CNC development education and research this highly focused textbook on the principles and development technologies of CNC controllers can also be used as a guide for those working on CNC development in industry *Industrial Robotics* Harry Colestock, 2005 This detailed reference shows how to achieve maximum productivity with robotics classifies robots according to their complexity and function and explains how to avoid common automation mistakes **Trajectory Planning for Coordinated Motion of a Robot and a Positioning Table Along Smooth and Sharp Cornered Paths** Musa Khalil Jouaneh, 1989 Robot Modeling and Kinematics Rachid Manseur, 2006 Robot Modeling and Kinematics teaches the fundamental topics of robotics using cutting edge visualization software and computer tools to illustrate topics and provide a comprehensive process of teaching and learning The book provides an introduction to robotics with an emphasis on the study of robotic arms their mathematical description and the equations describing their motion It teaches how to model robotic arms efficiently and analyze their kinematics The kinematics of robot manipulators is also

presented beginning with the use of simple robot mechanisms and progressing to the most complex robot manipulator structures While mathematically rigorous the book s focus is on ease of understanding of the concepts with interactive animated computer graphics illustrations and modeling software that allow clear understanding of the material covered in the book All necessary computations are concisely explained and software is provided that greatly eases the computational burden normally associated with robotics Written for use in a robotics course or as a professional reference Robot Modeling and Kinematics is an essential resource that provides a thorough understanding of the topics of modeling and kinematics

Optical Engineering ,1989 Publishes papers reporting on research and development in optical science and engineering and the practical applications of known optical science engineering and technology **The Specifications and Applications of Industrial Robots in Japan** ,1997 UK Robotics Research 1984 ,1984 *Industrial Robots* United States. Patent and Trademark Office. Office of Technology Assessment and Forecast,1982 **Industrial Robotics** Gordon M. Mair,1988 **Chartered Mechanical Engineer** ,1984 CME ,1984 Introduction to Robotics Arthur J. Critchlow,1985

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