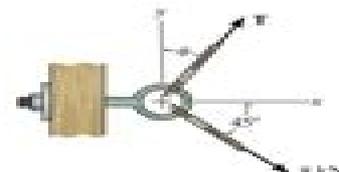


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2-2. If  $\theta = 60^\circ$  and  $F = 5 \text{ kN}$ , determine the magnitude of the resultant force acting on the eyebolt and its direction measured clockwise from the positive  $x$  axis.



The parallelogram law of addition and the triangular rule are shown in Figs. *a* and *b*, respectively.

Applying the law of cosines to Fig. *b*,

$$F_R = \sqrt{5^2 + 8^2 - 2(5)(8)\cos 105^\circ} \\ = 10.47 \text{ kN} = 10.5 \text{ kN}$$

Ans.

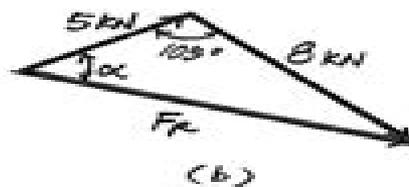
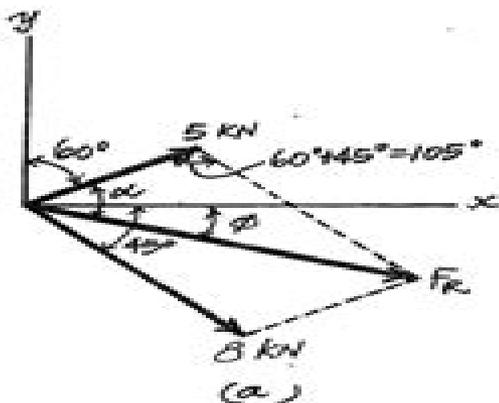
Applying the law of sines to Fig. *b* and using this result, yields

$$\frac{\sin \alpha}{8} = \frac{\sin 105^\circ}{10.47} \quad \alpha = 47.54^\circ$$

Thus, the direction angle  $\phi$  of  $F_R$  measured clockwise from the positive  $x$  axis is

$$\phi = \alpha - 30^\circ = 47.54^\circ - 30^\circ = 17.5^\circ$$

Ans.



# Engineering Mechanics Statics 12th Edition Chapter 2 Solutions

**Ryspek Usubamatov**



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This book highlights an analytical solution for the dynamics of axially rotating objects It also presents the theory of gyroscopic effects explaining their physics and using mathematical models of Euler s form for the motion of movable spinning objects to demonstrate these effects The major themes and approaches are represented by the spinning disc and the action of the system of interrelated inertial torques generated by the centrifugal and Coriolis forces as well as the change in the angular momentum The interrelation of inertial torques is based on the dependency of the angular velocities of the motions of the spinning objects around axes by the principle of mechanical energy conservation These kinetically interrelated torques constitute the fundamental principles of the mechanical gyroscope theory that can be used for any rotating objects of different designs like rings cones spheres paraboloids propellers etc Lastly the mathematical models for the gyroscopic effects are validated by practical tests The 2nd edition became necessary due to new development and corrections of mathematical expressions It contains new chapters about the Tippe top inversion and inversion of the spinning object in an orbital flight and the boomerang aerodynamics      *Engineering Mechanics 3* Dietmar Gross,Werner Hauger,Jörg Schröder,Wolfgang A. Wall,Sanjay Govindjee,2014-04-04 Dynamics is the third volume of a three volume textbook on Engineering Mechanics It was written with the intention of presenting to engineering students the basic concepts and principles of mechanics in as simple a form as the subject allows A second objective of this book is to guide the students in their efforts to solve problems in mechanics in a systematic manner The simple approach to the theory of mechanics allows for the different educational backgrounds of the students Another aim of this book is to provide engineering students as well as practising engineers with a basis to help them bridge the gaps between undergraduate studies advanced courses on mechanics and practical engineering problems The book contains numerous examples and their solutions Emphasis is placed upon student participation in solving the problems The contents of the book correspond to the topics normally covered in courses on basic engineering mechanics at universities and colleges Volume 1 deals with Statics Volume 2 contains Mechanics of Materials      **Engineering Mechanics** R. C. Hibbeler,2010 This volume presents the theory and applications of engineering mechanics Discussion of the subject areas of statics and dynamics covers such topics as engineering applications of the principles of static equilibrium of force systems acting on particles and rigid bodies structural analysis of trusses frames and machines forces in beams dry friction centroids and moments of inertia in addition to kinematics and kinetics of particles and rigid bodies Newtonian laws of motion work and energy and linear and angular momentum are also presented      Civil Engineering Hydraulics Abstracts ,1987      Government Gazette Cape of Good Hope (Colony),1870  
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