

Intelligent Systems, Control and Automation:
Science and Engineering

Matjaž Mihelj
Janez Podobnik

Haptics for Virtual Reality and Teleoperation

 Springer

Haptics For Virtual Reality And Teleoperation

Wenbin Ji

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Haptics For Virtual Reality And Teleoperation:

Haptics for Virtual Reality and Teleoperation Matjaž Mihelj, Janez Podobnik, 2012-12-14 This book covers all topics relevant for the design of haptic interfaces and teleoperation systems The book provides the basic knowledge required for understanding more complex approaches and more importantly it introduces all issues that must be considered for designing efficient and safe haptic interfaces Topics covered in this book provide insight into all relevant components of a haptic system The reader is guided from understanding the virtual reality concept to the final goal of being able to design haptic interfaces for specific tasks such as nanomanipulation The introduction chapter positions the haptic interfaces within the virtual reality context In order to design haptic interfaces that will comply with human capabilities at least basic understanding of human sensors motor system is required An overview of this topic is provided in the chapter related to human haptics The book does not try to introduce the state of the art haptic interface solutions because these tend to change quickly Only a careful selection of different kinematic configurations is shown to introduce the reader into this field Mathematical models of virtual environment collision detection and force rendering topics are strongly interrelated and are described in the next two chapters The interaction with the virtual environment is simulated with a haptic interface Impedance and admittance based approaches to haptic robot control are presented Stability issues of haptic interaction are analyzed in details and solutions are proposed for guaranteeing stable and safe operation Finally haptic interaction is extended to teleoperation systems Virtual fixtures which improve the teleoperation and human robot cooperation in complex environments are covered next and the last chapter presents nanomanipulation as one specific example of teleoperation

Haptics for Teleoperated Surgical Robotic Systems M. Tavakoli, 2008 An important obstacle in Minimally Invasive Surgery MIS is the significant degradation of haptic feedback sensation of touch to the surgeon about surgical instrument s interaction with tissue This monograph is concerned with devices and methods required for incorporating haptic feedback in master slave robotic MIS systems In terms of devices novel mechanisms are designed including a surgical end effector slave with full force sensing capabilities and a surgeon robot interface master with full force feedback capabilities Using the master slave system various haptic teleoperation control schemes are compared in terms of stability and performance and passivity based time delay compensation for haptic teleoperation over a long distance is investigated The monograph also compares haptic feedback with visual feedback and with substitution for haptic feedback by other sensory cues in terms of surgical task performance Sample Chapter s Introduction 1 826 KB Contents Introduction Sensorized Surgical Effector Slave Haptic User Interface Master Unilateral Teleoperation Control Bilateral Teleoperation Control Substitution for Haptic Feedback Bilateral Teleoperation Control Under Time Delay Readership Researchers in robotics teleoperation haptics virtual reality sensor technology human machine interaction and minimally invasive surgery and therapy

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These days people s desire for an evolutionary interface is strong The new model of human machine interaction is expected to be more realistic and immersive Haptic technology plays a key role in this regard It can be used for medical robotics and digital heritage applications Over three sections and five chapters this book examines these potential uses of haptics Chapters discuss using haptic feedback to improve robotic perception for medical simulations and to enhance digital heritage documentation **Haptics: Perception, Devices, Control, and Applications** Fernando Bello,Hiroyuki Kajimoto,Yon Visell,2016-07-01

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computerized techniques without becoming a programmer P 4 of cover *The Power of Touch* Elizabeth Pye,2007
Conference Magic Touch held at the Institute of Archaeology University College London 2004 published papers with aim to
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